

IISART

INTERNATIONAL INDUSTRY SOCIETY IN Advanced Rehabilitation Technology





1. Robotics

- **2. Non-Actuator Devices**
- **3. Functional Electrical Stimulation (FES)**
- 4. Sensor Technology
- **5. Virtual Reality**



1

ROBOTICS

Lower Extremities





EXOSKELETONS

Lower Extremities



System 4 Pro

Biodex Medical Systems

i Key Points

- Over 5,600 Peer Reviewed Citations in Support
- Objective Data
- Documented Progress, Need and Outcomes
- Research, Rehabilitation, Testing and Training
- 5 Modes of Operation, Passive, Isometric, Isokinetic, Isotonic and Reactive Eccentrics
- Capable of delivering concentric and eccentric contractions in 4 modes

System 4 Pro (Biodex Medical Systems, Shirley, New York, USA)

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Lokomat[®]Pro

Hocoma

i Key Points

- Adjustable exoskeleton for a physiologic gait pattern
- Assist-As-Needed support for optimal training challenge
- Augmented Performance Feedback for increased patient participation
- FreeD Module for balance activation and weight shift

Lokomat®Pro (Hocoma, Zurich)





Mehrholz et al., *Electromechanical-assisted training for walking after stroke*, Cochrane Database (2013)





Lokomat[®]Pro





Lokomat®Pro training (Landeskrankenhaus Hochzirl)



Erigo[®]Pro

Hocoma

Key Points

- Early and safe mobilization of severely impaired patients even in acute care
- Progressive verticalization up to 90°
- Cyclic leg movements 8-80 steps/min
- Cyclic leg loading (up to 50 kg) allows enhanced cardiovascular output
- Improved orthostatic tolerance through Functional Electrical Stimulation (FES)
- Sensorimotor stimulation improves patient awareness



Yoshida et al., *Cardiovascular response of individuals with spinal cord injury to dynamic functional electrical stimulation under orthostatic stress*, IEEE Trans Neural Syst Rehabil Eng (2013)



Erigo®Pro (CHUV, Lausanne)



Erigo[®]Pro





Erigo®Pro patient training (Landeskrankenhaus Hochzirl)





END-EFFECTORS

Lower Extremities



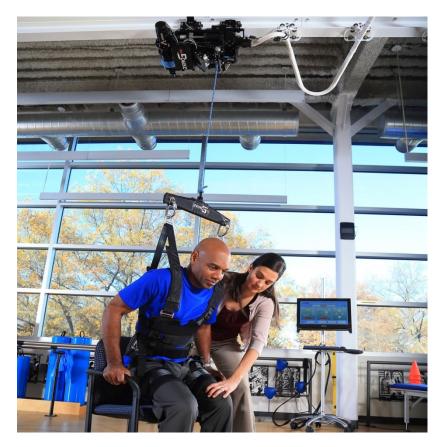
ZeroG[®] Gait and Balance System



Aretech

i Key Points

- Dynamic body-weight support compensates for weakness & poor coordination
- Robot tracks movements along a ceiling track
- Interactive games and balance training with biofeedback
- Lowers the risk of injury to patient & therapist
- Practice functional activities safely
- Monitor & track functional progress



ZeroG (Aretech, Ashburn, VA USA)

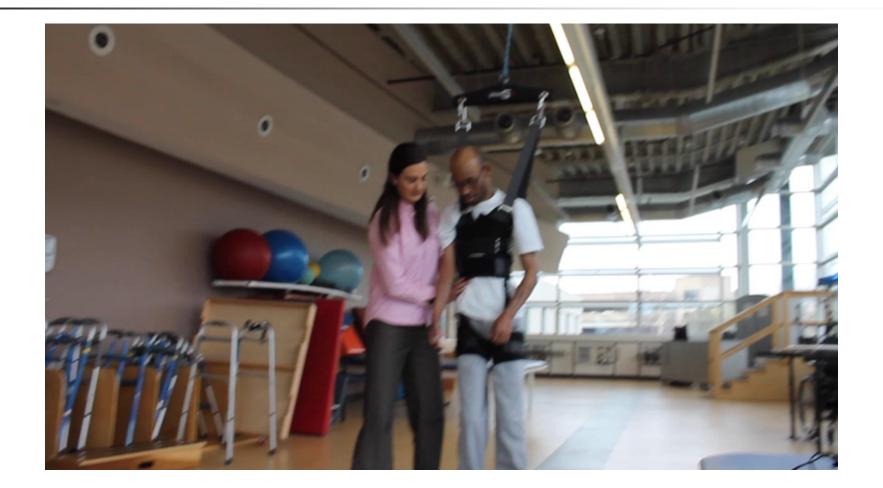


Hidler, et al. J Rehabil Res Dev. (2011) 48(4):287-98.









Functional Training with Dynamic Body-Weight Support



ZeroG®-Lite

Aretech

Treadmill-Based Gait Training System

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- Practice functional gait training safely
- Incline & reverse to walk up/down slopes
- Modulate intensity with dynamic body-weight support
- Lowers risk of injury to patient and therapist
- Orthopedic rehabilitation
- Improve cardiovascular function
- Monitor and track functional progress
- Ramp and wheelchair landing

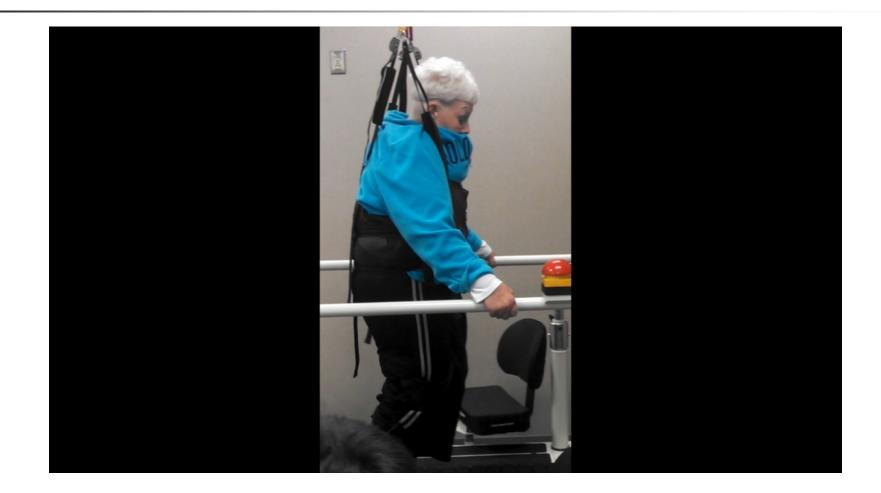


ZeroG-Lite (Aretech, Ashburn, VA USA)









Treadmill-Based Gait Training System





1

ROBOTICS

Upper Extremities





EXOSKELETONS

Upper Extremities



Hocoma

- Early rehabilitation training for severely affected patients
- Extensive 3D workspace (6 actuated dof)
- Assist-As-Needed support automatically adapts to patient's capabilities
- Augmented Performance Feedback increases motivation and trains activities of daily living
- Assessment Tools for objective analysis of patient's progress

Armeo®Power (Hocoma, Zurich)

Klamroth-Marganska et al., *Three-Dimensional, Task-Specific Robot Therapy Of The Arm After Stroke: A Multicentre, Parallel-Group Randomised Trial*, Lancet Neurol. (2014)













Armeo®Power Product Demo (Hocoma, Zurich)



System 4 Pro

Biodex Medical systems

i Key Points

- Visual Biofeedback
- Torque ranges from .5 ft-lbs to 500 ft-lbs
- Speed ranges from .25 deg/sec to 500 deg/sec
- Analog Output Signal Ranges from 100 2000hz
- Proproception mode incorporating Joint Position Sense and Kinesthesia testing and training
- Export Utility Software

System 4 Pro (Biodex Medical Systems, Shirley, New York, USA)

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Hand of Hope

Rehab-Robotics Company

Key Points

- 1st EMG-driven hand exoskeleton
- Active and Assistive device
- Hand and arm training
- Adjustable length for each finger
- Light, compact and portable
- Interactive games
- Easy-to-use interface
- Automatic report availability



The effects of post-stroke upper-limb training with an electromyography (EMG)-driven hand robot

20

X.L. Hu, K.Y. Tong X.J. Wei, W. Rong, E.A. Susanto, S.K. Ho Journal of Electromyography and Kinesiology 23 (2013) 1065–1074



Hand of Hope (Rehab-Robotics Company, Hong Kong)



Hand of Hope





Hand of Hope (Rehab-Robotics, Hong Kong), product demo



KINARM Exoskeleton Lab

BKIN Technologies Ltd

Key Points

- Assessment of range of neurological impairments associated with stroke, spinal cord injury, CP, Parkinson's
- Quantitative and objective measures of brain function and dysfunction through precise measurement of human behaviour
- Supports clinical researchers in the development of novel therapies for improved outcomes

KINARM Exoskeleton Lab (BKIN Technologies Ltd., Canada)





Semrau, J.A. et al. *Robotic identification of kinesthetic deficits after stroke.* Stroke. 44:3414-3421 (2013)

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KINARM Exoskeleton Lab





Demonstrates Visually Guided Reaching Task: limb coordination, use of vision, postural stability





END-EFFECTORS

Upper Extremities



Amadeo®

tyromotion

i Key Points

- Robot-assisted finger and hand therapy system
- Rehabilitation training for all levels of hand impairment
- Simulation of grasping and individual finger movements
- Force and ROM assessments
- Wide range of therapy applications, e.g. passive (CPM), assistive, active, spasticity and proprioceptive therapy
- Easily adjustable for children and adults





Sale et al., *Recovery of hand function with robot-assisted therapy in acute stroke patients: a randomized-controlled trial.* Int J Rehabilitation Research (2014).

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Amadeo® (tyromotion, Graz)



Amadeo®





Amadeo® product video: <u>https://www.youtube.com/watch?v=KA37ws_6-XM</u>

Amadeo R - Craig Hospital uses interactive technology for hand rehabilitation : <u>https://www.youtube.com/watch?v=Z_rk_21reA</u>



3D hin-feedback Individual applications for children and adults Task-oriented training with real objects

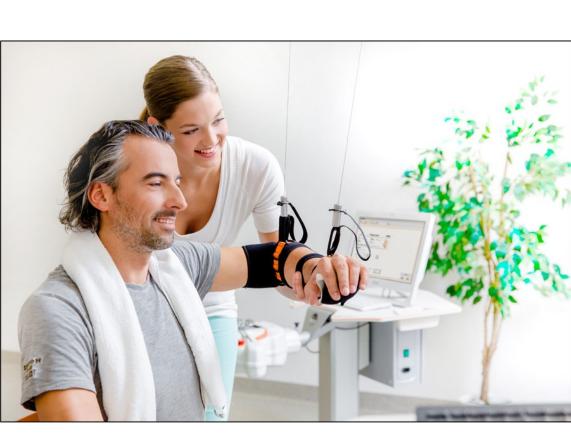
assist-as needed for functional reaching training

Bilateral, unilateral and symmetric arm training

tyromotion

Diego®







Mehrholz et al., Electromechanical and robot-assisted arm training for improving generic activities of daily living, arm function, and arm muscle strenght afters troke (Review), The Cochrane Library (2012)

Diego® (tyromotion, Graz)









Diego® product video: <u>https://www.youtube.com/watch?v=Ng5GyGldrMk</u>



KINARM End-Point Lab

BKIN Technologies Itd

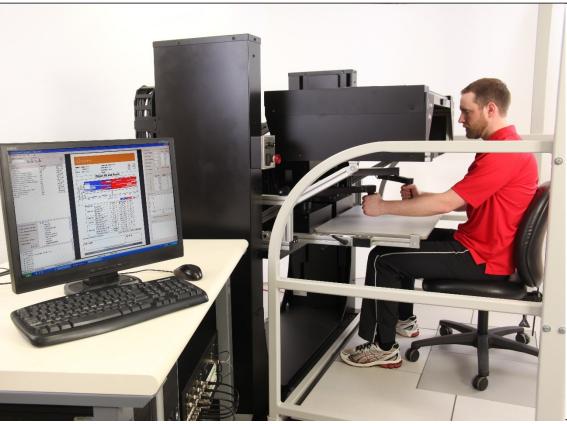
Key Points

- Assessment of range of neurological impairments associated with mTBI, sport concussion, TIA, MS, Alzheimer's
- Quantitative and objective measures of brain function and dysfunction through precise measurement of human behaviour
- Supports clinical researchers in the development of novel therapies for improved outcomes

KINARM End-Point Lab (BKIN Technologies Ltd., Canada)









Lowrey, C.R., et al. A Novel Robotic Task for Assessing Impairments in Bimanual Coordination Post-Stroke, Int J Phys Med Rehabil 2014, S3. (2014)

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KINARM End-Point Lab





Demonstrates Object Hit Test: a rapid bi-manual task that assesses assymetries in spatial awareness and use of upper limbs.

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2

NON-ACTUATOR DEVICES

Lower Extremities



Unweighting System and Gait Trainer 3

Biodex Medical Systems

i Key Points

- Dynamic partial weight bearing support system
- Adjustable harness with multiple lifting points for a comfortable, no slip patient experience.
- Ability to move overground without use of a treadmill
- Instrumented deck treadmill
- Visual biofeedback
- 0 deg/sec starting speed
- Documentation of gait compared to normative data

Unweighing System and Gait Trainer 3 (Biodex Medical Systems, Shirley, New York, USA)

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Patton J, Lewis E, Crombie G, Peshkin M, Colgate E, Santos J, Makhlin A, and Brown DA: A novel robotic device to enhance balance and mobility training post-stroke. Topics in Stroke Rehabilitation 15.2: 131-9. 2008

HDT Global

KineAssist-MX

i Key Points

- Driven by patient intent
- Reinforces neurological pathways and muscular systems
- Helps muscles relearn and reconnect through feedback and *self initiation*
- Transparent interaction with therapist
- Patients exercise at their own pace and with their own gait patterns
- Challenge-based training allows patients to *safely* learn from their mistakes and exceed their current capabilities







KineAssist-MX, HDT Global, Fredericksburg, VA USA

KineAssist-MX





Short Video Description





2

NON-ACTUATOR DEVICES

Upper Extremities



Colomer et al., *Efficacy Of Armeo®Spring During The Chronic Phase Of Stroke. Study In Mild To Moderate Cases Of Hemiparesis*, Neurologia (2013)

Simultaneous arm and hand therapy in an extensive 3D workspace

Arm orthosis with integrated weight compensation mechanism

Augmented Performance Feedback for motivational training of

Assessment Tools for objective analysis of patient progress

Armeo®Spring (Therapiezentrum am Goethe, Osnabrück)



Key Points

activities of daily living

Hocoma





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Armeo[®]Spring patient training (Rehaklinik Zihlschlacht)

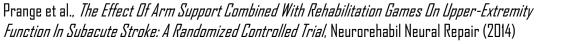


Armeo[®]Boom

Hocoma

i Key Points

- Arm Weight Support with low inertia for unrestricted and most physiological movements
- Augmented Performance Feedback with functional exercises and entertaining games for patient
- Assessment Tools to record patient performance



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Armeo®Boom (Hocoma, Zurich)











Armeo®Boom Product Demo (Hocoma, Zurich)



Balance System SD

Biodex Medical SystemsKey Points

Documented outcome against age based normative data

- Visual and audio Biofeedback
- Static and Dynamic modes
- 12 levels of stability in Dynamic mode
- 5 testing and 6 training modes
- Patient Data Collection Software Utilities



Balance System SD (Biodex Medical Systems, Shirley, New York, USA)







FUNCTIONAL ELECTRICAL STIMULATION



McLachlan AJ et al., *Changes in pulmonary function measures following a passive abdominal* functional electrical stimulation training program. The Journal of Spinal Cord Medicine. 2013, 36(2):97-103

RehaStim2

Hasomed Key Points

8 channel stimulator for NMES of paralyzed muscles

- Programmable to generate own FES patterns
- Sequence Mode with 50 pre installed programmes
- External Switch for manual triggering
- Science Mode© protocol for scientific application and PC control
- Used in world wide scientific projects





RehaStim2 (Hasomed, Magdeburg/Germany)



RehaMove

Hasomed

i Key Points

- Combination of FES and motor assisted movement therap
- Effective arm and leg treatment for neurological diseases with functional impairments

Kuhn D et al., Four weeks of functional electrical stimulated cycling after spinal

43

cord injury: a clinical cohort study. Int J Rehabil Res. 2014, 37(3):243-250

- Synchonized electrical pulses per communication interface
- Appropriate as home therapy

RehaMove (Hasomed, Magdeburg/Germany)











SENSOR TECHNOLOGY



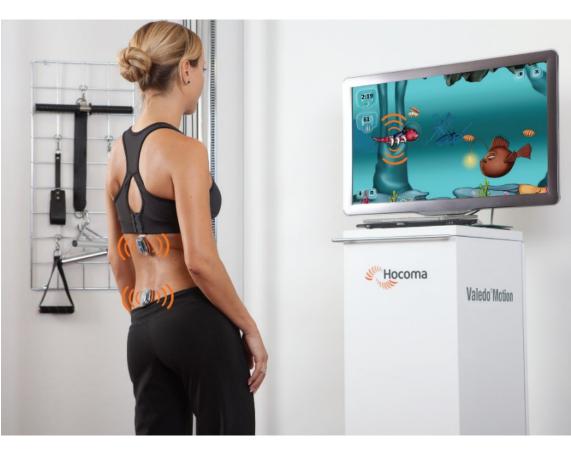
Valedo®Motion

Hocoma

i Key Points

- Medical back therapy supporting step-by-step movement learning
- Fun and engaging exercises for extensive training
- Real-Time Feedback improves body movement awareness
- Documentation and evaluation of therapy progress

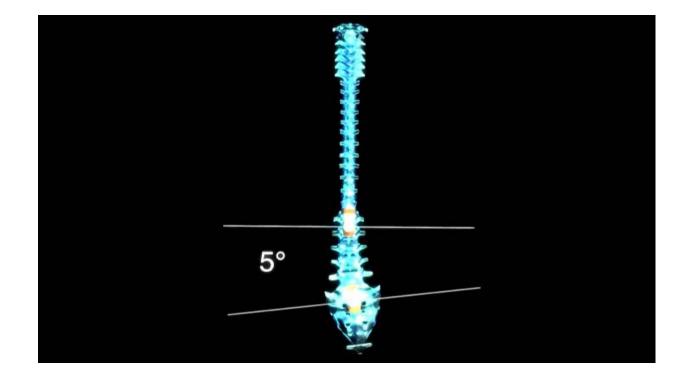






Valedo®Motion





Valedo[®]Motion

Examples for new technologies

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Valedo[®]Shape

Hocoma

i Key Points

- Rapid recording of the spine (frontal and sagittal planes)
- Visual representation of the spine
- Concise reports of measurements and assessments
- Comparison of measurements with healthy population

Valedo®Shape (Hocoma, Zurich)







Pablo®

tyromotion

i Key Points

- Ergonomic sensor handle for inter-active therapy
- Assessment and therapy for strength and mobility:
 - grip force (flexion & extension)
 - functional grips (e.g. pinch grip, key grip)
 - range of motion (RDM) & force control index (FCI)
- Increased application possibilities with additional system components: ball, board, belts, and pads
- Endless exercise options by combining software application, body area, and task









Seitz et al., *Monitoring of visuomotor coordination in healthy subjects and patients with stroke and Parkinson's disease: An application study using the PABLO®-device.* International J Neurorehabilitation (2014).

Pablo®





Pablo® product video: https://www.youtube.com/watch?v=JfrwmPdAtPA

Tymo®

tyromotion

i Key Points

- Portable wireless and thin therapy plate
- Assessment and inter-active therapy
 - with real time biofeedback
 - for training of postural control, weight bearing and weight shifting ability, and balance
 - used in various starting positions: supporting, sitting, sit-to-stand, and standing
 - static (force, CoP) & dynamic mode (1D & 2D rolling element)
- Medical device promoting rehabilitation goals



Borghese et al., *Computational intelligence and game design for effective athome stroke rehabilitation.* Games for Health J. (2013)





Tymo® (tyromotion, Graz)

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Tymo® product video: https://www.youtube.com/watch?v=laCmvtK6Me0







VIRTUAL REALITY



CAREN



Motekforce Link

i Key Points

- Computer Assisted Rehabilitation Environment
- Multi-sensory input for advanced rehabilitation protocols
- Interactive and dynamic Virtual Reality providing applied games for rehabilitation of movement discorders
- D-Flow application development software offering options to create custom research and clinical applications



CAREN (Motekforce Link, Amsterdam)



Geijtenbeek et al. (2011). "D-Flow: immersive virtual reality and real-time feedback for rehabilitation". Proceedings of the 10th International Conference on Virtual Reality Continuum and Its Applications in Industry (VRCAI '11). ACM, New York, NY, USA, pp. 201-208.

Examples for new technologies

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CAREN

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GRAIL

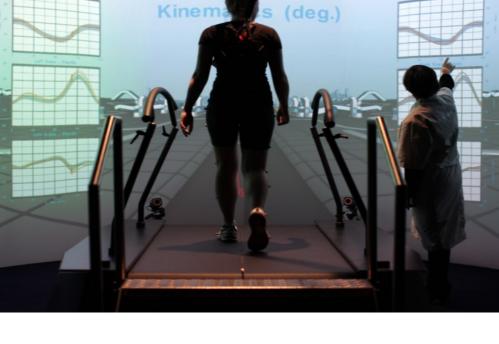
Motekforce Link

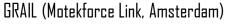
Key Points

- Full 3D gait analysis of multiple cycles within 30 minutes
- All gait parameters available in real-time for monitoring and intervention
- Self-paced mode enables patient to walk at a self selected pace
- Visual, mechanical or cognitive dual tasks for 'functional gait analysis' and gait training

Van der Krogt et al. *Overground versus self-paced treadmill walking in a virtual environment in children with cerebral palsy*, Gait & Posture (2014)

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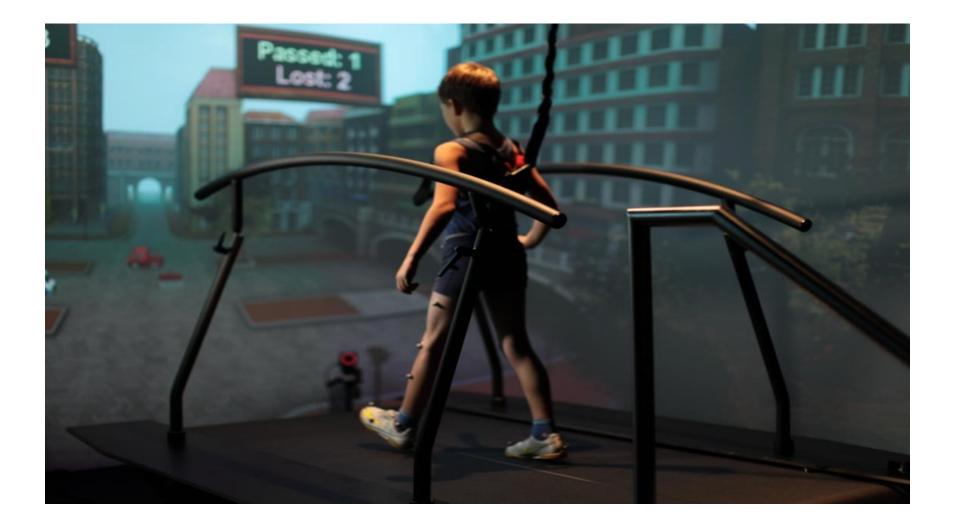
















Roerdink et al., *Online gait event detection using a large force platform* embedded in a treadmill(2008).

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C-Mill (Motekforce Link, Amsterdam)

Motekforce Link

Key Points 1

C-Mill

- Instrumented treadmill with projection
- Projection of cues relative to gait pattern
- Obstacle avoidance
- Train gait and gait adaptability
- Gait analysis with CueFors software





Sun(2014). *Effect of Virtual Reality Rehabilitation on Balance Function in Stroke Patients with Hemiplegia.*

DynSTABLE (Motekforce Link, Netherlands)

Motekforce Link

i Key Points

DynSTABLE

- Dynamic Balance Training and Assessment
- Objective Outcomes to Monitor Progression
- Immersive Virtual Environments Increase Patient Engagement
- Unique Moving Balance Platform







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Dynamic STability And Balance Learing Environment



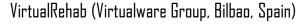
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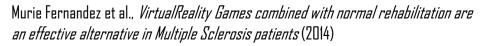
VirtualRehab

Virtualware Group

Key Points

- CE certified and clinically validated cloud-based physiotherapy videogame platform
- Incorporates motion capture technology
- Variety of engaging 3D styled games exercising different motor functions
- OnPremises version for clinical use and SaaS version for in-home TeleRehabilitation
- Used to treat Neurodegenerative diseases, Neuromuscular and Neurovascular disorders and to help improve mobility for the elderly





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VirtualRehab



VirtualRehab

Examples for new technologies

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International Industry Society in Advanced Rehabilitation Technology (IISART)

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